Product data sheet Characteristics

LXM32MD72N4

motion servo drive - Lexium 32 - three-phase supply voltage 208/480V - 7 kW





Main

| W IS | | |
|---------------------------|---|--|
| | | |
| Main | | |
| Range of product | Lexium 32 | |
| Product or component type | Motion servo drive | |
| Device short name | LXM32M | |
| Format of the drive | Book | |
| Network number of phases | Three phase | |
| [Us] rated supply voltage | 200240 V - 1510 % 380480 V - 1510 % | |
| Supply voltage limits | 170264 V 323528 V | |
| Supply frequency | 50/60 Hz - 55 % | |
| Network frequency | 47.563 Hz | |
| EMC filter | Integrated | |
| Continuous output current | 24 A at 8 kHz | |
| Output current 3s peak | 72 A for 5 s | |
| Maximum continuous power | 6500 W at 230 V | |
| Nominal power | 5 kW at 230 V 8 kHz 7 kW at 400 V | |
| Line current | 23.5 A 43 % at 380 V, with external line choke of 1 mH 19.5 A 55 % at 480 V, with external line choke of 1 mH 14.6 A 129 % at 480 V, without line choke | |
| Complementary | | |
| Switching frequency | 8 kHz | |
| Overvoltage category | III | |
| Maximum leakage current | 30 mA | |
| Output voltage | <= power supply voltage | |
| Electrical isolation | Between power and control | |
| Type of cable | Single-strand IEC cable (temperature: 50 °C) copper 90 °C XLPE/EPR | |

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| Electrical connection | Terminal, clamping capacity: 3 mm ² , AWG 12 (CN8) |
|-------------------------|--|
| Tightening torque | CN8: 0.5 N.m |
| Discrete input number | 2 capture discrete input(s) |
| Discrete input type | Capture (CAP terminals) |
| Sampling duration | 0.25 ms |
| Discrete input voltage | 24 V DC for capture |
| Discrete input logic | Positive (compliment of STO_A, compliment of STO_B) at State 0: < 5 V at State 1: > 15 V conforming to EN/IEC 61131-2 type 1 |
| Response time | <= 5 ms compliment of STO_A, compliment of STO_B |
| Discrete output number | 3 |
| Discrete output type | Logic output(s) (DO)24 V DC |
| Discrete output voltage | <= 30 V DC |
| Discrete output logic | Positive or negative (DO) conforming to EN/IEC 61131-2 |
| Contact bounce time | <= 1 ms for compliment of STO_A, compliment of STO_B |
| Braking current | 50 mA |
| Response time on output | 250 μs (DO) for discrete output(s) |
| Control signal type | Pulse train output (PTO) RS422 <500 kHz <100 m |
| Protection type | Against reverse polarity: inputs signal |
| Safety function | STO (safe torque off), integrated |
| Safety level | SIL 3 conforming to EN/IEC 61508 |
| Communication interface | Modbus, integrated |
| Connector type | RJ45 (labelled CN7) for Modbus |
| Commissioning port | 2-wire RS485 multidrop for Modbus |
| Transmission rate | 9600, 19200, 38400 bps for bus length of 40 m for Modbus |
| Number of addresses | 1247 for Modbus |
| Status LED | 1 LED (red)servo drive voltage: |
| Signalling function | Display of faults 7 segments |
| Marking | CE |
| Operating position | Vertical +/- 10 degree |
| Product compatibility | Servo motor BMH (140 mm, 2 motor stacks) |
| Width | 108 mm |
| Height | 270 mm |
| Depth | 237 mm |
| Net weight | 4.8 kg |

Environment

| Electromagnetic compatibility | Conducted EMC, class A group 1 conforming to EN 55011 |
|---------------------------------------|--|
| Standards | EN/IEC 61800-3 |
| Product certifications | CSA |
| IP degree of protection | IP20 conforming to EN/IEC 60529 |
| Vibration resistance | 1 gn (f= 13150 Hz) conforming to EN/IEC 60068-2-6 |
| Shock resistance | 15 gn for 11 ms conforming to EN/IEC 60028-2-27 |
| Pollution degree | 2 conforming to EN/IEC 61800-5-1 |
| Environmental characteristic | Classes 3C1 conforming to IEC 60721-3-3 |
| Relative humidity | Class 3K3 (5 to 85 %) without condensation conforming to IEC 60721-3-3 |
| Ambient air temperature for operation | 050 °C conforming to UL |
| Ambient air temperature for storage | -2570 °C |
| Type of cooling | Integrated fan |
| Operating altitude | <= 1000 m without derating |
| | |

Packing Units

Package 1 Weight

5.506 kg

| Package 1 Height | 1.420 dm |
|------------------|----------|
| Package 1 width | 2.760 dm |
| Package 1 Length | 3.250 dm |

Offer Sustainability

| Green Premium product | |
|---|--|
| REACh Declaration | |
| Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration | |
| Yes | |
| Yes | |
| China RoHS declaration | |
| Product Environmental Profile | |
| End of Life Information | |
| The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins | |
| | |

| Contractual | warrantv |
|-------------|----------|
| Contractua | wantanty |

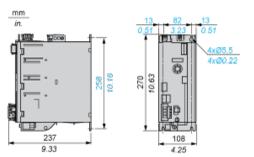
Warranty

18 months

LXM32MD72N4

Lexium 32 Servo Drive

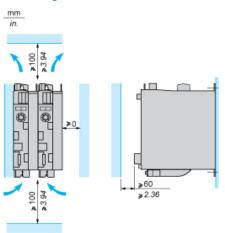
Dimensions



LXM32MD72N4

Lexium 32 Motion Control Servo Drives

Mounting Recommendations



LXM32•U45M2, •U90M2 and LXM32•U60N4 servo drives are cooled by natural convection. LXM32•D18M2, •D30M2, LXM32 •D12N4, •D18N4, •D30N4 and •D72N4servo drives have an integrated fan.

When installing the servo drive in the enclosure, follow the instructions below with regard to the temperature and protection index:

- Provide sufficient cooling of the servo drive
- Do not mount the servo drive near heat sources
- Do not mount the servo drive on flammable materials
- Do not heat the servo drive cooling air by currents of hot air from other equipment and components, for example from an external braking resistor
- Mount the servo drive vertically (± 10%)
- If the servo drive is used above its thermal limits, control stops due to overtemperature

NOTE: For cables that are connected via the underside of the servo drive, a free space \geq 200 mm/7.87 in. is required under the unit to comply with the bending radius of the connection cables.

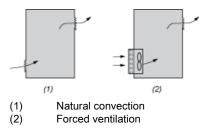
| Ambient temperature | Mounting distances | Instructions to be followed |
|---------------------|--------------------|---|
| 0°C+ 50°C | d ≥ 0 mm | - |
| + 50°C+ 60°C | | Reduce the output current by 2.2% per °C above 50°C |

NOTE: Do not use insulated enclosures, as they have a poor level of conductivity.

Recommendations for Mounting in an Enclosure

To ensure good air circulation in the servo drive:

- Fit ventilation grilles on the enclosure.
- Ensure that ventilation is adequate, otherwise install a forced ventilation unit with a filter.



- Any apertures and/or fans must provide a flow rate at least equal to that of the servo drive fans (refer to characteristics).
- Use special filters with IP 54 protection.

Mounting in Metal Enclosure (IP 54 Degree of Protection)

The servo drive must be mounted in a dust and damp proof enclosure in certain environmental conditions, such as dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. In these cases, Lexium 32 servo drives can be installed in an enclosure where the internal temperature must not exceed 60°C.