



## Main

|                              |                         |
|------------------------------|-------------------------|
| Range of product             | Easy Altivar 310        |
| Product or component type    | Variable speed drive    |
| Product specific application | Simple machine          |
| Assembly style               | With heat sink          |
| Device short name            | ATV310                  |
| Network number of phases     | Three phase             |
| [Us] rated supply voltage    | 380...460 V - 15...10 % |
| Motor power kW               | 0.75 kW                 |
| Motor power hp               | 1 hp                    |

## Complementary

|                                  |  |
|----------------------------------|--|
| Product destination              | Asynchronous motors  |
| Quantity per set                 | Set of 1   |
| EMC filter                       | Without EMC filter   |
| Supply frequency                 | 50/60 Hz +/- 5 %   |
| Communication port protocol      | Modbus   |
| Connector type                   | RJ45 (on front face) for Modbus  |
| Physical interface               | 2-wire RS 485 for Modbus   |
| Transmission frame               | RTU for Modbus   |
| Transmission rate                | 4800 bit/s<br>9600 bit/s<br>19200 bit/s<br>38400 bit/s   |
| Number of addresses              | 1...247 for Modbus   |
| Communication service            | Read holding registers (03) 29 words<br>Write single register (06) 29 words<br>Write multiple registers (16) 27 words<br>Read/write multiple registers (23) 4/4 words<br>Read device identification (43) |
| Line current                     | 3.1 A  |
| Apparent power                   | 2.5 kVA  |
| Prospective line I <sub>sc</sub> | 5 kA   |

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

|                                     |  |
|-------------------------------------|--|
| Continuous output current           | 2.3 A at 4 kHz   |
| Maximum transient current           | 3.5 A for 60 s   |
| Power dissipation in W              | 28.83 W at In  |
| Speed drive output frequency        | 0.5...400 Hz   |
| Nominal switching frequency         | 4 kHz  |
| Switching frequency                 | 2...12 kHz adjustable  |
| Speed range                         | 1...20   |
| Transient overtorque                | 170...200 % of nominal motor torque depending on drive rating and type of motor  |
| Braking torque                      | Up to 150 % of nominal motor torque with braking resistor at high inertia<br>Up to 70 % of nominal motor torque without braking resistor   |
| Asynchronous motor control profile  | Sensorless flux vector control<br>Quadratic voltage/frequency ratio<br>Sensorless flux vector control  |
| Motor slip compensation             | Adjustable<br>Preset in factory  |
| Output voltage                      | 380...460 V three phase  |
| Electrical connection               | Terminal, clamping capacity: 1.5...2.5 mm <sup>2</sup> (L1, L2, L3, PA+, PB, U, V, W)  |
| Tightening torque                   | 0.8...1 N.m  |
| Insulation                          | Electrical between power and control   |
| Supply                              | Internal supply for reference potentiometer: 5 V (4.75...5.25 V)DC, <10 mA with overload and short-circuit protection<br>Internal supply for logic inputs: 24 V (20.4...28.8 V)DC, <100 mA with overload and short-circuit protection  |
| Analogue input number               | 1  |
| Analogue input type                 | Configurable current AI1 0...20 mA 250 Ohm<br>Configurable voltage AI1 0...10 V 30 kOhm<br>Configurable voltage AI1 0...5 V 30 kOhm  |
| Discrete input number               | 4  |
| Discrete input type                 | Programmable LI1...LI4 24 V 18...30 V  |
| Discrete input logic                | Negative logic (sink), > 16 V (state 0), < 10 V (state 1), input impedance 3.5 kOhm<br>Positive logic (source), 0...< 5 V (state 0), > 11 V (state 1)  |
| Sampling duration                   | 10 ms for analogue input<br>20 ms, tolerance +/- 1 ms for logic input  |
| Linearity error                     | +/- 0.3 % of maximum value for analogue input  |
| Analogue output number              | 1  |
| Analogue output type                | AO1 software-configurable voltage: 0...10 V, impedance: 470 Ohm, resolution 8 bits<br>AO1 software-configurable current: 0...20 mA, impedance: 800 Ohm, resolution 8 bits  |
| Discrete output number              | 2  |
| Discrete output type                | Logic output LO+, LO-<br>Protected relay output R1A, R1B, R1C 1 C/O  |
| Minimum switching current           | 5 mA at 24 V DC for logic relay  |
| Maximum switching current           | 2 A at 250 V AC on inductive load cos phi = 0.4 L/R = 7 ms for logic relay<br>2 A at 30 V DC on inductive load cos phi = 0.4 L/R = 7 ms for logic relay<br>3 A at 250 V AC on resistive load cos phi = 1 L/R = 0 ms for logic relay<br>4 A at 30 V DC on resistive load cos phi = 1 L/R = 0 ms for logic relay |
| Acceleration and deceleration ramps | U<br>U<br>S  |
| Braking to standstill               | By DC injection, <30 s   |
| Protection type                     | Line supply overvoltage<br>Line supply undervoltage<br>Overcurrent between output phases and earth<br>Overheating protection<br>Short-circuit between motor phases<br>Against input phase loss in three-phase<br>Thermal motor protection via the drive by continuous calculation of I <sup>2</sup> t          |
| Frequency resolution                | Analog input: converter A/D, 10 bits<br>Display unit: 0.1 Hz   |
| Time constant                       | 20 ms +/- 1 ms for reference change  |
| Operating position                  | Vertical +/- 10 degree   |

|            |        |
|------------|--------|
| Height     | 130 mm |
| Width      | 72 mm  |
| Depth      | 143 mm |
| Net weight | 0.7 kg |

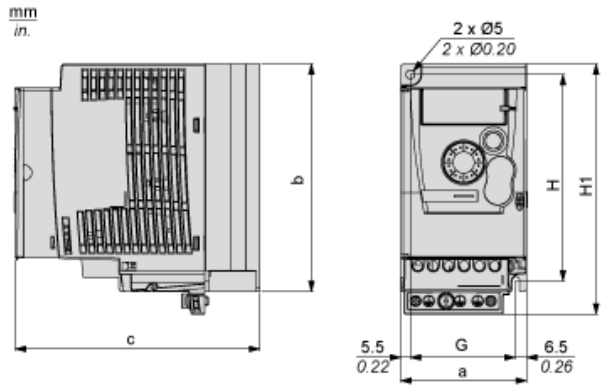
## Environment

|                                       |  |
|---------------------------------------|--|
| Electromagnetic compatibility         | Electrical fast transient/burst immunity test - test level: level 4 conforming to EN/IEC 61000-4-4<br>Electrostatic discharge immunity test - test level: level 3 conforming to EN/IEC 61000-4-2<br>Immunity to conducted disturbances - test level: level 3 conforming to EN/IEC 61000-4-6<br>Radiated radio-frequency electromagnetic field immunity test - test level: level 3 conforming to EN/IEC 61000-4-3<br>Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11<br>Surge immunity test - test level: level 3 conforming to EN/IEC 61000-4-5 |
| Standards                             | EN/IEC 61800-5-1<br>EN/IEC 61800-5-1   |
| IP degree of protection               | IP20 without blanking plate on upper part<br>IP41 top  |
| Pollution degree                      | 2 conforming to EN/IEC 61800-5-1   |
| Environmental characteristic          | Dust pollution resistance class 3S2 conforming to EN/IEC 60721-3-3<br>Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3   |
| Shock resistance                      | 15 gn conforming to EN/IEC 60068-2-27 for 11 ms  |
| Relative humidity                     | 5...95 % without condensation conforming to IEC 60068-2-3<br>5...95 % without dripping water conforming to IEC 60068-2-3   |
| Ambient air temperature for storage   | -25...70 °C  |
| Ambient air temperature for operation | -10...55 °C without derating<br>55...60 °C protective cover from the top of the drive removed with current derating 2.2 % per °C   |
| Operating altitude                    | <= 1000 m without derating   |

## Packing Units

|                              |          |
|------------------------------|----------|
| Unit Type of Package 1       | PCE      |
| Number of Units in Package 1 | 1        |
| Package 1 Weight             | 1.028 kg |
| Package 1 Height             | 13 cm    |
| Package 1 width              | 18.6 cm  |
| Package 1 Length             | 19.2 cm  |

Dimensions



Dimensions in mm

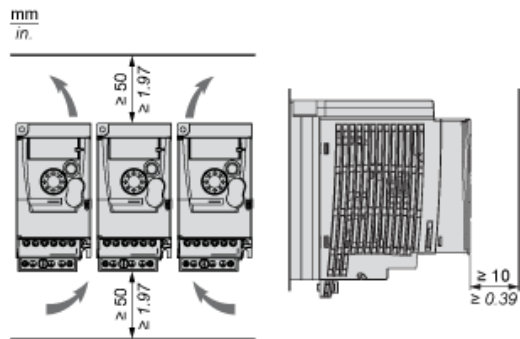
| a  | b   | c   | G  | H   | H1  | Ø | For screws |
|----|-----|-----|----|-----|-----|---|------------|
| 72 | 130 | 140 | 60 | 118 | 143 | 5 | M4         |

Dimensions in in.

| a    | b    | c    | G    | H    | H1   | Ø    | For screws |
|------|------|------|------|------|------|------|------------|
| 2.83 | 5.12 | 5.51 | 2.36 | 4.65 | 5.63 | 0.20 | M4         |

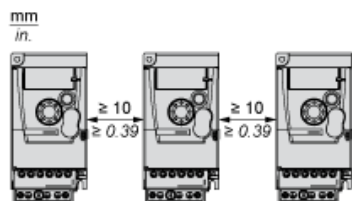
Mounting Recommendations

Clearance

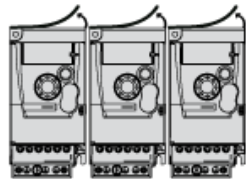


Mounting Types

Mounting Type A

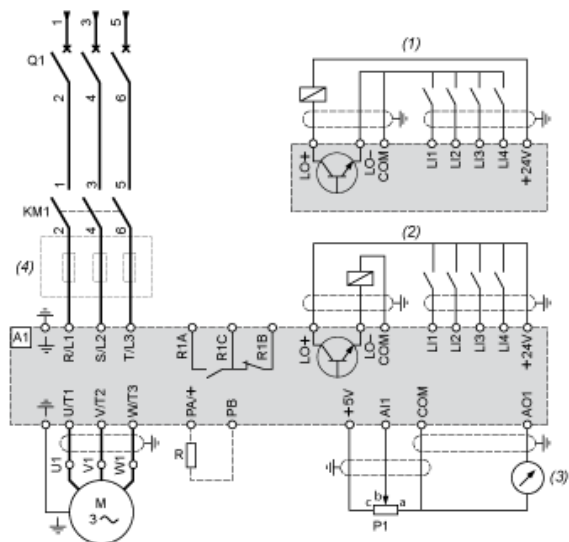


Mounting Type B



Remove the protective cover from the top of the drive.

Three-Phase Power Supply Wiring Diagram



- A1 : Drive
- KM1 : Contactor (only if a control circuit is needed)
- P1 : 2.2 kΩ reference potentiometer. This can be replaced by a 10 kΩ potentiometer (maximum).
- Q1 : Circuit breaker
- R : Braking resistor (optional)
- (1) Negative logic (Sink)
- (2) Positive logic (Source) (factory set configuration)
- (3) 0...10 V or 0...20 mA
- (4) Line choke three-phase (optional)